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Laboratory Com-

Linear Groups

Simplicity of

# Simple Finite Groups of Lie Type

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Euler Circle

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#### Introduction

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## Introduction

### Definition 1

A group G is a set paired with a binary operation on its elements,  $\cdot$  that satisfies the following axioms:

- 1 Closure: for all  $a, b \in G$ ,  $a \cdot b \in G$ .
- 2 Associativity: for all  $a, b, c \in G$ ,  $a \cdot (b \cdot c) = (a \cdot b) \cdot c$ .
- **3** Existence of Identity: There exists some  $1 \in G$  such that for all  $a \in G$ ,  $1 \cdot a = a \cdot 1 = a$ .
- 4 Existence of Inverses: For all  $a \in G$ , there exists some  $a^{-1} \in G$  such that  $a \cdot a^{-1} = a^{-1} \cdot a = 1$ .

### Definition 2

If G has a subset, S, which is also a group under the same operation as G, we call S a subgroup,  $S \leq G$ .

### Definition 3

We call a subgroup N of a group G normal if for all  $g \in G$  and all  $n \in N$ ,  $gng^{-1} \in N$ .

### Definition 4

We call a group G simple if the whole group G and the trivial subgroup  $\{1\}$  are the only normal subgroups of G.

The Hölder Program is a program to classify all finite groups, which involves classifying all simple finite groups (completed in the Enormous Theorem), then finding all ways of "putting simple groups together."

### Theorem 5 (The Enormous Theorem)

Every simple finite group G can be classified as

- **1** A cyclic group of prime order.
- 2 An alternating group of order greater than 5.
- 3 A group of Lie type. These are further broken down into 16 infinite families.
- 4 One of 26 Sporadic groups.

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Whenever we have a subset S of a group G, where all elements of G are a product of elements of S and their inverses, this is called a set of *generators* of G.

### Theorem 6

All simple finite groups are generated by 2 of their elements.

### Definition 7

A *field* is a set  $\mathbb{F}$  with two binary operations, addition and multiplication defined on all elements satisfying the following axioms:

- $\blacksquare$  F is an abelian group under addition with identity 0.
- 2  $\mathbb{F}\setminus\{0\}$  also written as  $\mathbb{F}^{\times}$  is an abelian group under multiplication with identity 1.
- Multiplication distributes over addition: for all  $a, b, c \in \mathbb{F}$ , a(b+c)=ab+ac. This also implies that 0a=0 for all  $a\in \mathbb{F}$ .

We say  $\mathbb{F}_q$  is the unique field with q elements.

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Lie groups are groups that are also manifolds, and the group operation and taking inverses correspond to smooth maps of the manifold.

### Example

 $GL_n(\mathbb{R})$  is a submanifold of  $\mathbb{R}^{n^2}$ , and also a group.

The classical groups are finite groups of lie type related to subgroups of  $GL_n(q)$  when  $\mathbb{F}$  is a finite field.

### Theorem 8

$$|GL_n(q)| = (q^n - 1)(q^n - q) \dots (q^n - q^{n-1}).$$

### Proof.

For a matrix to be in  $GL_n(q)$  it must have nonzero determinant, so its columns must be linearly independent. There are  $q^n$  possible values for the first column, and we subtract 1 to avoid the case where all entries are 0. The second column cannot be one of the q multiples of the first so there are  $q^n - q$  possibilities and so on.

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### Definition 9

Given a group G, its center, Z(G) is the subgroup such that for all  $a \in Z(G)$  and  $b \in G$ ,  $a \cdot b = b \cdot a$ .

The center of  $GL_n(q)$  is the set of scalar matrices  $\lambda I_n$  such that  $\lambda \in \mathbb{F}_q$  We can quotient  $GL_n(q)$  by its center to get  $PGL_n(q)$ . Since there are q-1 possibilities for  $\lambda$ ,  $|Z(GL_n(q))=q-1|$  and  $|PGL_n(q)|=\frac{1}{q-1}|GL_n(q)|$ .

### Definition 10

We define the special linear group,  $SL_n(q) \leq GL_n(q)$  to be the subgroup of matrices with determinant 1.

Its center also consists of scalar matrices, and since  $\det(\lambda I_n) = \lambda^n$ ,  $\lambda^n = 1$ . We can take the quotient of  $SL_n(q)$  by its center to get  $PSL_n(q)$ , which is one of the 16 infinite families of Lie groups in the classification theorem.

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### Definition 11

A transvection in a vector space, V is a linear transformation that fixes a hyperplane H and has determinant 1.

Transvections are shear transformations of vector spaces. Given a transvection, T, then we can choose a basis such that T has a matrix of the following from:

$$\begin{bmatrix} 1 & 1 & 0 & \cdots & 0 \\ 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & \ddots & \vdots & 0 \\ \vdots & \vdots & \cdots & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}.$$

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### Lemma 12

 $SL_n(q)$  is generated by transvections.

### Lemma 13

If N is a normal subgroup of  $SL_n(q)$ , and  $A \in N$  but  $A \notin Z(SL_n(q)$ , then there exists some transvection  $T \in N$ .

### Theorem 14

The groups  $PSL_n(q)$  when  $n \geq 3$  are simple.

### Proof.

We show that  $PSL_n(q)$  is simple by showing that if a normal subgroup N of  $SL_n(q)$  contains some  $A \notin Z(SL_n(q))$  then  $N = SL_n(q)$  If N contains a transvection T, then for all transvections  $t \in SL_n(q)$  there exists  $g \in SL_n(q)$  such that  $gTg^{-1}=t$  since all transvections are similar. Thus,  $t \in N$ , and since  $SL_n(q)$  is generated by transvections, and N contains all transvections,  $SL_n(q) = N$ . Therefore  $PSL_n(q)$  is simple.