Quaternions and Algebras

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A quaternion is a number of the form q = t + xi + yj + zk for real numbers t, x, y, z.

An octonion is a number of the form $x_{\infty} + \sum_{n=0}^{\infty} x_n i_n$ where the i_n satisfy $i_n^2 = -1$ and

 $i_{n+1}i_{n+2} = i_{n+4} = -i_{n+2}i_{n+1}$ $i_{n+2}i_{n+4} = i_{n+1} = -i_{n+4}i_{n+2}$ $i_{n+4}i_{n+1} = i_{n+2} = -i_{n+1}i_{n+4}$

with indices taken modulo 7.

They were invented by William Rowan Hamilton in 1843. A plaque on the Broom Bridge in Dublin, Ireland commemorates his discovery of the equation $i^2 = j^2 = k^2 = ijk = -1$.

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A field is a set combined with addition and multiplication operations with additive and multiplicative identities 0 and 1. Quaternion algebras need to have a basis 1, i, j, ij satisfying $i^2 = a$, $j^2 = b$, and ij = -ji.

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$$\overline{\mathbf{3}} \ \overline{\alpha\beta} = \overline{\beta}\overline{\alpha} \text{ for all } \alpha, \beta \in \mathbf{B}.$$

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Definition 1

A similarity from Q to another quadratic form $Q' : V' \to F$ is a pair (f, u) where $f : V \xrightarrow{\sim} V'$ is an F-linear isomorphism and $u \in F^{\times}$ satisfy Q'(f(x)) = uQ(x) for all $x \in V$. An isometry is a similarity with u = 1.

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Definition 2

A quadratic form is a map $Q: V \rightarrow F$ on an F-vector space V satisfying:

- 1 $Q(ax) = a^2 Q(x)$ for all $a \in F$ and $x \in V$; and
- **2** The map $T: V \times V \rightarrow F$ defined by

$$T(x,y) = Q(x+y) - Q(x) - Q(y)$$

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is F-bilinear.

Well, then our algebra B would be defined as follows:

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i² + i = a
 j² = b
 ij = j(i + 1)

A simple algebra is one that only has $\{0\}$ and itself as two-sided ideals.

A representation of B is a vector space V together with a homomorphism from B to the set of endomorphisms from V to F. A representation is given by a left or right B-module.

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A Hurwitz quaternion is a quaternion with t, x, y, z integers or half-integers. The Hurwitz units include the basis units, their negatives, and the quaternions with each component 1/2 or -1/2.

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A primitive Hurwitz integer can be factored into Hurwitz primes with factorization unique to unit-migration.



What are the only composition algebras?

Theorem 3

 \mathbb{R} , \mathbb{C} , \mathbb{H} , and \mathbb{O} are the only composition algebras.

This theorem also proves the nonexistence of an algebra of higher dimension, a proposed algebra with 16 dimensions as a result of extending the octonions.

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Multiplication laws:



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$$[xy] = [x][y]$$

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$$\bullet [xy] = [x][y]$$

$$\bullet [xy, xz] = [x][y, z]$$

•
$$2[x, u][y, z] = [xy, uz] + [xz, uy]$$

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Conjugation laws:

Multiplication laws:

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Conjugation laws:

•
$$[xy, z] = [y, \overline{x}z]$$

Multiplication laws:

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Conjugation laws:

$$[xy, z] = [y, \overline{x}z]$$
$$\overline{\overline{x}} = x$$

Multiplication laws:

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Conjugation laws:

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Doubling laws:

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Doubling laws:

$$[a + ib, c + id] = [a, c] + [b, d]$$

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Multiplication laws:

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$$\begin{bmatrix} a + ib, c + id \end{bmatrix} = [a, c] + [b, d]$$
$$= \overline{a + ib} = \overline{a} - ib$$

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Multiplication laws:

Conjugation laws:

• $[xy, z] = [y, \overline{x}z]$ • $\overline{\overline{x}} = x$

$$\overline{xy} = \overline{y}\overline{x}$$

Doubling laws:

$$[a+ib, c+id] = [a, c] + [b, d]$$

$$\overline{a+ib} = \overline{a} - ib$$

$$(a+ib)(c+id) = (ac - d\overline{b}) + i(cb + \overline{a}d)$$

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Quaternions were invented by Hamilton to model 3D rotations. They are practical because they can be stored with less memory than a rotation matrix. The use of quaternions also avoids gimbal lock, which is when two of the three rotation axes line up.



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